PAC-Bayesian Inequalities for Martingales

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Abstract—We present a set of high-probability inequalities that control the concentration of weighted averages of multiple (possibly uncountably many) simultaneously evolving and interdependent martingales. Our results extend the PAC-Bayesian (probably approximately correct) analysis in learning theory from the i.i.d. setting to martingales opening the way for its application to importance weighted sampling, reinforcement learning, and other interactive learning domains, as well as many other domains in probability theory and statistics, where martingales are encountered. We also present a comparison inequality that bounds the expectation of a convex function of a martingale difference sequence shifted to the [0,1] interval by the expectation of the same function of independent Bernoulli random variables. This inequality is applied to derive a tighter analog of Hoeffding–Azuma's inequality.

Index Terms—Bernstein's inequality, Hoeffding-Azuma's inequality, martingales, PAC-Bayesian bounds.

I. INTRODUCTION

ARTINGALES are one of the fundamental tools in probability theory and statistics for modeling and studying sequences of random variables. Some of the most well known and widely used concentration inequalities for individual martingales are Hoeffding-Azuma's and Bernstein's inequalities [1]-[3]. We present a comparison inequality that bounds the expectation of a convex function of a martingale difference sequence shifted to the [0,1] interval by the expectation of the same function of independent Bernoulli random variables. We apply this inequality in order to derive a tighter analog of Hoeffding-Azuma's inequality for martingales.

More importantly, we present a set of inequalities that make it possible to control weighted averages of multiple simultaneously evolving and interdependent martingales (see Fig. 1 for an illustration). The inequalities are especially interesting when the number of martingales is uncountably infinite and the standard

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$$\mathcal{H} \left\{ \begin{array}{ccccc} \vdots & \vdots & \ddots & \vdots \\ \updownarrow & \updownarrow & \ddots & \ddots \\ \bar{M}_{1}(h_{1}) & \stackrel{?}{\smile} & \bar{M}_{2}(h_{1}) & \stackrel{?}{\smile} & \cdots & \stackrel{?}{\smile} & \bar{M}_{n}(h_{1}) \\ \updownarrow & & \updownarrow & & \updownarrow \\ \bar{M}_{1}(h_{2}) & \stackrel{?}{\smile} & \bar{M}_{2}(h_{2}) & \stackrel{?}{\smile} & \cdots & \stackrel{?}{\smile} & \bar{M}_{n}(h_{2}) \\ \updownarrow & & \updownarrow & & & \updownarrow \\ \bar{M}_{1}(h_{3}) & \stackrel{?}{\smile} & \bar{M}_{2}(h_{3}) & \stackrel{?}{\smile} & \cdots & \stackrel{?}{\smile} & \bar{M}_{n}(h_{3}) \\ \updownarrow & & \updownarrow & & \updownarrow & & \updownarrow \\ \vdots & & \vdots & & \ddots & \vdots \\ \hline & & & & & & \downarrow \\ \hline & & & & & & \downarrow \\ \hline & & & & & & \downarrow \\ \hline \end{array} \right.$$

Fig. 1. Illustration of an infinite set of simultaneously evolving and interdependent martingales. $\mathcal H$ is a space that indexes the individual martingales. For a fixed point $h \in \mathcal H$, the sequence $\bar M_1(h), \bar M_2(h), \ldots, \bar M_n(h)$ is a single martingale. The arrows represent the dependences between the values of the martingales: the value of a martingale h at time i, denoted by $\bar M_i(h)$, depends on $\bar M_j(h')$ for all $j \leq i$ and $h' \in \mathcal H$ (everything that is "before" and "concurrent" with $\bar M_i(h)$ in time; some of the arrows are omitted for clarity). A mean value of the martingales with respect to a probability distribution ρ over $\mathcal H$ is given by $\langle \bar M_n, \rho \rangle$. Our high-probability inequalities bound $|\langle \bar M_n, \rho \rangle|$ simultaneously for a large class of ρ .

union bound over the individual martingales cannot be applied. The inequalities hold with high probability simultaneously for a large class of averaging laws ρ . In particular, ρ can depend on the sample.

One possible application of our inequalities is an analysis of importance-weighted sampling. Importance-weighted sampling is a general and widely used technique for estimating properties of a distribution by drawing samples from a different distribution. Via proper reweighting of the samples, the expectation of the desired statistics based on the reweighted samples from the controlled distribution can be made identical to the expectation of the same statistics based on unweighted samples from the desired distribution. Thus, the difference between the observed statistics and its expected value forms a martingale difference sequence. Our inequalities can be applied in order to control the deviation of the observed statistics from its expected value. Furthermore, since the averaging law ρ can depend on the sample, the controlled distribution can be adapted based on its outcomes from the preceding rounds, for example, for denser sampling in the data-dependent regions of interest. See [4] for an example of an application of this technique in reinforcement learning.

Our concentration inequalities for weighted averages of martingales are based on a combination of Donsker-Varadhan's variational formula for relative entropy [5]–[7] with bounds on certain moment-generating functions of martingales, including Hoeffding-Azuma's and Bernstein's inequalities, as well as the new inequality derived in this paper.

In a nutshell, the Donsker–Varadhan's variational formula implies that for a probability space $(\mathcal{H}, \mathcal{B})$, a bounded real-valued random variable Φ , and any two probability distributions

 π and ρ over \mathcal{H} (or, if \mathcal{H} is uncountably infinite, two probability density functions), the expected value $\mathbb{E}_{\rho}[\Phi]$ is bounded as

$$\mathbb{E}_{\rho}[\Phi] \le \mathrm{KL}(\rho \| \pi) + \ln \mathbb{E}_{\pi}[e^{\Phi}] \tag{1}$$

where $\mathrm{KL}(\rho \| \pi)$ is the KL-divergence (relative entropy) between two distributions [8]. We can also think of Φ as $\Phi = \phi(h)$, where $\phi(h)$ is a measurable function $\phi : \mathcal{H} \to \mathbb{R}$. Inequality (1) can then be written using the dot-product notation

$$\langle \phi, \rho \rangle \le \text{KL}(\rho \| \pi) + \ln \left(\langle e^{\phi}, \pi \rangle \right)$$
 (2)

and $\mathbb{E}_{\rho}[\phi] = \langle \phi, \rho \rangle$ can be thought of as a weighted average of ϕ with respect to ρ (for countable \mathcal{H} , it is defined as $\langle \phi, \rho \rangle = \sum_{h \in \mathcal{H}} \phi(h) \rho(h)$, and for uncountable \mathcal{H} , it is defined as $\langle \phi, \rho \rangle = \int_{\mathcal{H}} \phi(h) \rho(h) dh$).\(^1\)

The weighted averages $\langle \phi, \rho \rangle$ on the left-hand side of (2) are the quantities of interest and the inequality allows us to relate all possible averaging laws ρ to a single "reference" distribution π . (Sometimes, π is also called a "prior" distribution, since it has to be selected before observing the sample.) We emphasize that inequality (2) is a deterministic relation. Thus, by a single application of Markov's inequality to $\langle e^\phi, \pi \rangle$, we obtain a statement that holds with high probability for all ρ simultaneously. The quantity $\ln \langle e^\phi, \pi \rangle$, known as the cumulant-generating function of ϕ , is closely related to the moment-generating function of ϕ . The bound on $\ln \langle e^\phi, \pi \rangle$, after some manipulations, is achieved via the bounds on moment-generating functions, which are identical to those used in the proofs of Hoeffding–Azuma's, Bernstein's, or our new inequality, depending on the choice of ϕ .

Donsker-Varadhan's variational formula for relative entropy laid the basis for PAC-Bayesian analysis in statistical learning theory [9]–[12], where PAC is an abbreviation for the probably approximately correct learning model introduced by Valiant [13]. PAC-Bayesian analysis provides high-probability bounds on the deviation of weighted averages of empirical means of sets of independent random variables from their expectations. In the learning theory setting, the space \mathcal{H} usually corresponds to a hypothesis space; the function $\phi(h)$ is related to the difference between the expected and empirical error of a hypothesis h; the distribution π is a prior distribution over the hypothesis space; and the distribution ρ defines a randomized classifier. The randomized classifier draws a hypothesis h from \mathcal{H} according to ρ at each round of the game and applies it to make the prediction on the next sample. PAC-Bayesian analysis supplied generalization guarantees for many influential machine learning algorithms, including support vector machines [14], [15], linear classifiers [16], and clustering-based models [17], to name just a few of them.

We show that PAC-Bayesian analysis can be extended to martingales. A combination of PAC-Bayesian analysis with Hoeffding-Azuma's inequality was applied by Lever *et al.* [18] in the analysis of U-statistics. The results presented here are

¹The complete statement of Donsker–Varadhan's variational formula for relative entropy states that under appropriate conditions $\mathrm{KL}(\rho || \pi) = \sup_{\phi} \left(\langle \phi, \rho \rangle - \ln \langle e^{\phi}, \pi \rangle \right)$, where the supremum is achieved by $\phi(h) = \ln \frac{\rho(h)}{\pi(h)}$. However, in our case, the choice of ϕ is directly related to the values of the martingales of interest and the free parameters in the inequality are the choices of ρ and π . Therefore, we are looking at the inequality in the form of (1) and a more appropriate name for it is "change of measure inequality."

both tighter and more general, and make it possible to apply PAC-Bayesian analysis in new domains, such as, for example, reinforcement learning [4].

II. MAIN RESULTS

We first present our new inequalities for individual martingales, and then present the inequalities for weighted averages of martingales. All the proofs are provided in the appendix.

A. Inequalities for Individual Martingales

Our first lemma is a comparison inequality that bounds expectations of convex functions of martingale difference sequences shifted to the [0,1] interval by expectations of the same functions of independent Bernoulli random variables. The lemma generalizes a previous result by Maurer for independent random variables [19]. The lemma uses the following notation: for a sequence of random variables X_1, \ldots, X_n , we use $X_1^i := X_1, \ldots, X_i$ to denote the first i elements of the sequence.

Lemma 1: Let X_1,\ldots,X_n be a sequence of random variables, such that $X_i\in[0,1]$ with probability 1 and $\mathbb{E}[X_i|X_1^{i-1}]=b_i$ for $i=1,\ldots,n$. Let Y_1,\ldots,Y_n be independent Bernoulli random variables, such that $\mathbb{E}[Y_i]=b_i$. Then, for any convex function $f:[0,1]^n\to\mathbb{R}$

$$\mathbb{E}\left[f(X_1,\ldots,X_n)\right] \leq \mathbb{E}\left[f(Y_1,\ldots,Y_n)\right].$$

Let $\mathrm{kl}(p\|q) = p\ln\frac{p}{q} + (1-p)\ln\frac{1-p}{1-q}$ be an abbreviation for $\mathrm{KL}\left([p,1-p]\big|\big|[q,1-q]\right)$, where [p,1-p] and [q,1-q] are Bernoulli distributions with biases p and q, respectively. By Pinsker's inequality [8]

$$|p-q| \le \sqrt{\mathrm{kl}(p||q)/2}$$

which means that a bound on kl(p||q) implies a bound on the absolute difference between the biases of the Bernoulli distributions.

We apply Lemma 1 in order to derive the following inequality, which is an interesting generalization of an analogous result for i.i.d. variables. The result is based on the method of types in information theory [8].

Lemma 2: Let X_1,\ldots,X_n be a sequence of random variables, such that $X_i\in[0,1]$ with probability 1 and $\mathbb{E}[X_i|X_1^{i-1}]=b$. Let $S_n:=\sum_{i=1}^n X_i$. Then

$$\mathbb{E}\left[e^{n\operatorname{kl}\left(\frac{1}{n}S_n\|b\right)}\right] \le n+1. \tag{3}$$

Note that in Lemma 2 the conditional expectation $\mathbb{E}[X_i|X_1^{i-1}]$ is identical for all i, whereas in Lemma 1 there is no such restriction. Combination of Lemma 2 with Markov's inequality leads to the following analog of Hoeffding–Azuma inequality.

Corollary 3: Let X_1, \ldots, X_n be as in Lemma 2. Then, for any $\delta \in (0,1)$, with probability greater than $1-\delta$

$$\operatorname{kl}\left(\frac{1}{n}S_n \middle\| b\right) \le \frac{1}{n} \ln \frac{n+1}{\delta}.\tag{4}$$

 S_n is a terminal point of a random walk with bias b after n steps. By combining Corollary 3 with Pinsker's inequality, we

can obtain a more explicit bound on the deviation of the terminal point from its expected value, $|S_n-bn| \leq \sqrt{\frac{n}{2} \ln \frac{n+1}{\delta}}$, which is similar to the result we can obtain by applying Hoeffding–Azuma's inequality. However, in certain situations, the less explicit bound in the form of kl is significantly tighter than Hoeffding–Azuma's inequality and it can also be tighter than Bernstein's inequality. A detailed comparison is provided in Section III.

B. PAC-Bayesian Inequalities for Weighted Averages of Martingales

Next, we present several inequalities that control the concentration of weighted averages of multiple simultaneously evolving and interdependent martingales. The first result shows that the classical PAC-Bayesian theorem for independent random variables [12] holds in the same form for martingales. The result is based on combination of Donsker–Varadhan's variational formula for relative entropy with Lemma 2. In order to state the theorem, we need a few definitions.

Let $(\mathcal{H},\mathcal{B})$ be a probability space. Let $\bar{X}_1,\ldots,\bar{X}_n$ be a sequence of random functions, such that $\bar{X}_i:\mathcal{H}\to[0,1]$. Assume that $\mathbb{E}[\bar{X}_i|\bar{X}_1,\ldots,\bar{X}_{i-1}]=\bar{b}$, where $\bar{b}:\mathcal{H}\to[0,1]$ is a deterministic function (possibly unknown). This means that $\mathbb{E}[\bar{X}_i(h)|\bar{X}_1,\ldots,\bar{X}_{i-1}]=\bar{b}(h)$ for each i and h. Note that for each $h\in\mathcal{H}$, the sequence $\bar{X}_1(h),\ldots,\bar{X}_n(h)$ satisfies the condition of Lemma 2.

Let $\bar{S}_n := \sum_{i=1}^n \bar{X}_i$. In the following theorem, we are bounding the mean of \bar{S}_n with respect to any probability measure ρ over \mathcal{H} .

Theorem 4 (PAC-Bayes-kl Inequality): Fix a reference distribution π over \mathcal{H} . Then, for any $\delta \in (0,1)$, with probability greater than $1-\delta$ over $\bar{X}_1,\ldots,\bar{X}_n$, for all distributions ρ over \mathcal{H} simultaneously

$$\operatorname{kl}\left(\left\langle \frac{1}{n}\bar{S}_{n}, \rho \right\rangle \middle\| \langle \bar{b}, \rho \rangle\right) \leq \frac{KL(\rho || \pi) + \ln \frac{n+1}{\delta}}{n}.$$
 (5)

By Pinsker's inequality, Theorem 4 implies that

$$\left| \left\langle \frac{1}{n} \bar{S}_n, \rho \right\rangle - \left\langle \bar{b}, \rho \right\rangle \right| = \left| \left\langle \left(\frac{1}{n} \bar{S}_n - \bar{b} \right), \rho \right\rangle \right|$$

$$\leq \sqrt{\frac{\text{KL}(\rho || \pi) + \ln \frac{n+1}{\delta}}{2n}}. \tag{6}$$

However, if $\langle \frac{1}{n} \bar{S}_n, \rho \rangle$ is close to zero or one, inequality (5) is significantly tighter than (6).

The next result is based on a combination of Donsker-Varadhan's variational formula for relative entropy with Hoeffding-Azuma's inequality. This time let $\bar{Z}_1,\ldots,\bar{Z}_n$ be a sequence of random functions, such that $\bar{Z}_i:\mathcal{H}\to\mathbb{R}$. Let \bar{Z}_1^i be an abbreviation for a subsequence of the first i random functions in the sequence. We assume that $\mathbb{E}[\bar{Z}_i|\bar{Z}_1^i]=\bar{0}$. In other words, for each $h\in\mathcal{H}$, the sequence $Z_1(h),\ldots,Z_n(h)$ is a martingale difference sequence.

Let $\bar{M}_i := \sum_{j=1}^i \bar{Z}_j$. Then, for each $h \in \mathcal{H}$, the sequence $\bar{M}_1(h), \ldots, \bar{M}_n(h)$ is a martingale. In the following theorems,

we bound the mean of \bar{M}_n with respect to any probability measure ρ on \mathcal{H} .

Theorem 5: Assume that $\bar{Z}_i: \mathcal{H} \to [\alpha_i, \beta_i]$. Fix a reference distribution π over \mathcal{H} and $\lambda > 0$. Then, for any $\delta \in (0, 1)$, with probability greater than $1 - \delta$ over \bar{Z}_1^n , for all distributions ρ over \mathcal{H} simultaneously

$$|\langle \bar{M}_n, \rho \rangle| \le \frac{\mathrm{KL}(\rho \| \pi) + \ln \frac{2}{\delta}}{\lambda} + \frac{\lambda}{8} \sum_{i=1}^{n} (\beta_i - \alpha_i)^2.$$
 (7)

We note that we cannot minimize inequality (7) simultaneously for all ρ by a single value of λ . In the following theorem, we take a grid of λ -s in a form of a geometric sequence and for each value of $\mathrm{KL}(\rho\|\pi)$, we pick a value of λ from the grid, which is the closest to the one that minimizes (7). The result is almost as good as what we could achieve if we would minimize the bound just for a single value of ρ .

Theorem 6 (PAC-Bayes Hoeffding-Azuma Inequality): Assume that \bar{Z}_1^n is as in Theorem 5. Fix a reference distribution π over \mathcal{H} . Take an arbitrary number c>1. Then, for any $\delta\in(0,1)$, with probability greater than $1-\delta$ over \bar{Z}_1^n , for all distributions ρ over \mathcal{H} simultaneously

$$|\langle \bar{M}_n, \rho \rangle| \le \frac{1+c}{2\sqrt{2}} \sqrt{\left(\text{KL}(\rho || \pi) + \ln \frac{2}{\delta} + \epsilon(\rho) \right) \sum_{i=1}^{n} (\beta_i - \alpha_i)^2}$$
(8)

where

$$\epsilon(\rho) = \frac{\ln 2}{2 \ln c} \left(1 + \ln \left(\frac{\mathrm{KL}(\rho \| \pi)}{\ln \frac{2}{\delta}} \right) \right).$$

Our last result is based on a combination of Donsker–Varadhan's variational formula with a Bernstein-type inequality for martingales. Let $\bar{V}_i:\mathcal{H}\to\mathbb{R}$ be such that $\bar{V}_i(h):=\sum_{j=1}^i\mathbb{E}\left[\bar{Z}_j(h)^2\Big|\bar{Z}_1^{j-1}\right]$. In other words, $\bar{V}_i(h)$ is the variance of the martingale $\bar{M}_i(h)$ defined earlier. Let $\|\bar{Z}_i\|_{\infty}=\sup_{h\in\mathcal{H}}\bar{Z}_i(h)$ be the L_{∞} norm of \bar{Z}_i .

Theorem 7: Assume that $\|\bar{Z}_i\|_{\infty} \leq K$ for all i with probability 1 and pick λ , such that $\lambda \leq 1/K$. Fix a reference distribution π over \mathcal{H} . Then, for any $\delta \in (0,1)$, with probability greater than $1-\delta$ over \bar{Z}_1^n , for all distributions ρ over \mathcal{H} simultaneously

$$|\langle \bar{M}_n, \rho \rangle| \le \frac{\mathrm{KL}(\rho \| \pi) + \ln \frac{2}{\delta}}{\lambda} + (e - 2)\lambda \langle \bar{V}_n, \rho \rangle.$$
 (9)

As in the previous case, the right-hand side of (9) cannot be minimized for all ρ simultaneously by a single value of λ . Furthermore, \bar{V}_n is a random function. In the following theorem, we take a similar grid of λ -s, as we did in Theorem 6, and a union bound over the grid. Picking a value of λ from the grid closest to the value of λ that minimizes the right-hand side of (9) yields almost as good result as we would get if we would minimize (9) for a single choice of ρ . In this approach, the variance \bar{V}_n can be replaced by a sample-dependent upper bound. For example, in

importance-weighted sampling, such an upper bound is derived from the reciprocal of the sampling distribution at each round [4].

Theorem δ (PAC-Bayes Bernstein Inequality): Assume that $\|\bar{Z}_i\|_{\infty} \leq K$ for all i with probability 1. Fix a reference distribution π over \mathcal{H} . Pick an arbitrary number c>1. Then, for any $\delta\in(0,1)$, with probability greater than $1-\delta$ over \bar{Z}_1^n , simultaneously for all distributions ρ over \mathcal{H} that satisfy

$$\sqrt{\frac{\mathrm{KL}(\rho\|\pi) + \ln\frac{2\nu}{\delta}}{(e-2)\langle\bar{V}_n, \rho\rangle}} \le \frac{1}{K}$$
 (10)

we have

$$|\langle \bar{M}_n, \rho \rangle| \le (1+c) \sqrt{(e-2)\langle \bar{V}_n, \rho \rangle} \left(\text{KL}(\rho \| \pi) + \ln \frac{2\nu}{\delta} \right)$$
(11)

where

$$\nu = \left\lceil \frac{\ln\left(\sqrt{\frac{(e-2)n}{\ln\frac{2}{\delta}}}\right)}{\ln c} \right\rceil + 1 \tag{12}$$

and for all other ρ

$$|\langle \bar{M}_n, \rho \rangle| \le 2K \left(\text{KL}(\rho || \pi) + \ln \frac{2\nu}{\delta} \right).$$
 (13)

([x] is the smallest integer value that is larger than x.)

III. COMPARISON OF THE INEQUALITIES

In this section, we remind the reader of Hoeffding–Azuma's and Bernstein's inequalities for individual martingales and compare them with our new kl-form inequality. Then, we compare inequalities for weighted averages of martingales with inequalities for individual martingales.

A. Background

We first recall Hoeffding-Azuma's inequality [1], [2]. For a sequence of random variables Z_1, \ldots, Z_n , we use $Z_1^i := Z_1, \ldots, Z_i$ to denote the first i elements of the sequence.

Lemma 9 (Hoeffding–Azuma's Inequality): Let Z_1,\ldots,Z_n be a martingale difference sequence, such that $Z_i\in [\alpha_i,\beta_i]$ with probability 1 and $\mathbb{E}[Z_i|Z_1^{i-1}]=0$. Let $M_i=\sum_{j=1}^i Z_j$ be the corresponding martingale. Then, for any $\lambda\in\mathbb{R}$

$$\mathbb{E}[e^{\lambda M_n}] < e^{(\lambda^2/8) \sum_{i=1}^n (\beta_i - \alpha_i)^2}.$$

By combining Hoeffding–Azuma's inequality with Markov's inequality and taking $\lambda = \sqrt{\frac{8 \ln \frac{2}{\delta}}{\sum_{i=1}^{n} (\beta_i - \alpha_i)^2}}$, it is easy to obtain the following corollary.

Corollary 10: For M_n defined in Lemma 9 and $\delta \in (0,1)$, with probability greater than $1 - \delta$

$$|M_n| \le \sqrt{\frac{1}{2} \ln\left(\frac{2}{\delta}\right) \sum_{i=1}^n (\beta_i - \alpha_i)^2}.$$

The next lemma is a Bernstein-type inequality [3], [20]. We provide the proof of this inequality in Appendix C, the proof is a part of the proof of [21, Th. 1].

Lemma 11 (Bernstein's Inequality): Let Z_1,\ldots,Z_n be a martingale difference sequence, such that $|Z_i| \leq K$ with probability 1 and $\mathbb{E}[Z_i|Z_1^{i-1}] = 0$. Let $M_i := \sum_{j=1}^i Z_j$ and let $V_i := \sum_{j=1}^i \mathbb{E}[(Z_j)^2|Z_1^{j-1}]$. Then, for any $\lambda \in [0,\frac{1}{K}]$

$$\mathbb{E}\left[e^{\lambda M_n - (e-2)\lambda^2 V_n}\right] \le 1.$$

By combining Lemma 11 with Markov's inequality, we obtain that for any $\lambda \in [0, \frac{1}{K}]$ and $\delta \in (0, 1)$, with probability greater than $1 - \delta$

$$|M_n| \le \frac{1}{\lambda} \ln \frac{2}{\delta} + \lambda (e - 2) V_n. \tag{14}$$

 V_n is a random variable and can be replaced by an upper bound. Inequality (14) is minimized by $\lambda^* = \sqrt{\frac{\ln \frac{2}{\delta}}{(e-2)V_n}}$. Note that λ^* depends on V_n and is not accessible until we observe the entire sample. We can bypass this problem by constructing the same grid of λ -s, as the one used in the proof of Theorem 8, and taking a union bound over it. Picking a value of λ closest to λ^* from the grid leads to the following corollary. In this bounding technique, the upper bound on V_n can be sample-dependent, since the bound holds simultaneously for all λ -s in the grid. Despite being a relatively simple consequence of Lemma 11, we have not seen this result in the literature. The corollary is tighter than an analogous result by Beygelzimer $et\ al.\ [21,\ Th.\ 1]$.

Corollary 12: For M_n and V_n as defined in Lemma 11, c > 1 and $\delta \in (0, 1)$, with probability greater than $1 - \delta$, if

$$\sqrt{\frac{\ln\frac{2\nu}{\delta}}{(e-2)V_n}} \le \frac{1}{K} \tag{15}$$

then

$$|M_n| \le (1+c)\sqrt{(e-2)V_n \ln \frac{2\nu}{\delta}}$$

where ν is defined in (12), and otherwise

$$|M_n| \le 2K \ln \frac{2\nu}{\delta}.$$

The technical condition (15) follows from the requirement of Lemma 11 that $\lambda \in [0, \frac{1}{K}]$.

B. Comparison

We first compare inequalities for individual martingales in Corollaries 3, 10, and 12.

Comparison of Inequalities for Individual Martingales: The comparison between Corollaries 10 and 12 is relatively straightforward. We note that the assumption $\mathbb{E}[Z_i|Z_1^{i-1}]=0$ implies that $\alpha_i \leq 0$ and that $V_n \leq \sum_{i=1}^n \max\{\alpha_i^2,\beta_i^2\} \leq \sum_{i=1}^n (\beta_i - \alpha_i)^2$. Hence, Corollary 12 (derived from Bernstein's inequality) matches Corollary 10 (derived from Hoeffding–Azuma's inequality) up to minor constants and logarithmic factors in the general case, and can be much tighter when the variance is small.

The comparison with the kl inequality in Corollary 3 is a bit more involved. As we mentioned after Corollary 3, its combination with Pinsker's inequality implies that $|S_n - bn| \le \sqrt{\frac{n}{2} \ln \frac{n+1}{\delta}}$, where $S_n - bn$ is a martingale corresponding to the martingale difference sequence $Z_i = X_i - b$. Thus, Corollary 3 is at least as tight as Hoeffding–Azuma's inequality in Corollary 10, up to a factor of $\sqrt{\ln \frac{n+1}{2}}$. This is also true if $X_i \in [\alpha_i, \beta_i]$ (rather than [0,1]), as long as we can simultaneously project all X_i -s to the [0,1] interval without losing too much.

Tighter upper bounds on the kl divergence show that in certain situations, Corollary 3 is actually much tighter than Hoeffding–Azuma's inequality. One possible application of Corollary 3 is the estimation of the value of the drift b of a random walk from empirical observation S_n . If S_n is close to zero, it is possible to use a tighter bound on kl, which states that for p>q, we have $p\leq q+\sqrt{2q\,\mathrm{kl}(q\|p)}+2\mathrm{kl}(q\|p)$ [15]. From this inequality, we obtain that with probability greater than $1-\delta$

$$b \le \frac{1}{n} S_n + \sqrt{\frac{\frac{2}{n} S_n \ln \frac{n+1}{\delta}}{n}} + \frac{2 \ln \frac{n+1}{\delta}}{n}.$$

The aforementioned inequality is tighter than Hoeffding–Azuma inequality whenever $\frac{1}{n}S_n < 1/8$. Since kl is convex in each of its parameters, it is actually easy to invert it numerically, and thus avoid the need to resort to approximations in practice. In a similar manner, tighter bounds can be obtained when S_n is close to n.

The comparison of kl inequality in Corollary 3 with Bernstein's inequality in Corollary 12 is not as equivocal as the comparison with Hoeffding–Azuma's inequality. If there is a bound on V_n that is significantly tighter than n, Bernstein's inequality can be significantly tighter than the kl inequality, but otherwise it can also be the opposite case. In the example of estimating a drift of a random walk without prior knowledge on its variance, if the empirical drift is close to zero or to n, the kl inequality is tighter. In this case, the kl inequality is comparable with empirical Bernstein's bounds [22]–[24].

Comparison of Inequalities for Individual Martingales With PAC-Bayesian Inequalities for Weighted Averages of Martingales: The "price" that is paid for considering weighted averages of multiple martingales is the KL-divergence $\mathrm{KL}(\rho \| \pi)$ between the desired mixture weights ρ and the reference mixture weights π . (In the case of PAC-Bayes Hoeffding-Azuma inequality, Theorem 6, there is also an additional minor term

originating from the union bound over the grid of λ -s.) Note that for $\rho = \pi$, the KL term vanishes.

IV. DISCUSSION

We presented a comparison inequality that bounds expectation of a convex function of martingale difference type variables by expectation of the same function of independent Bernoulli random variables. This inequality enables us to reduce a problem of studying continuous dependent random variables on a bounded interval to a much simpler problem of studying independent Bernoulli random variables.

As an example of an application of the inequality, we derived an analog of Hoeffding–Azuma's inequality for martingales. Our result is always comparable to Hoeffding–Azuma's inequality up to a logarithmic factor and in cases where the empirical drift of a corresponding random walk is close to the region boundaries, it is tighter than Hoeffding–Azuma's inequality by an order of magnitude. It can also be tighter than Bernstein's inequality for martingales, unless there is a tight bound on the martingale variance.

Finally, but most importantly, we presented a set of inequalities on concentration of weighted averages of multiple simultaneously evolving and interdependent martingales. These inequalities are especially useful for controlling uncountably many martingales, where standard union bounds cannot be applied. Martingales are one of the most basic and important tools for studying time-evolving processes and we believe that our results will be useful for multiple domains. One such application in analysis of importance-weighted sampling in reinforcement learning was already presented in [4].

APPENDIX A

PROOF OF THE RESULTS FOR INDIVIDUAL MARTINGALES

Proof of Lemma 1: The proof follows the lines of the proof of Maurer [19, Lemma 3]. Any point $\bar{x}=(x_1,\ldots,x_n)\in [0,1]^n$ can be written as a convex combination of the extreme points $\bar{\eta}=(\eta_1,\ldots,\eta_n)\in\{0,1\}^n$ in the following way:

$$\bar{x} = \sum_{\bar{\eta} \in \{0,1\}^n} \left(\prod_{i=1}^n [(1-x_i)(1-\eta_i) + x_i \eta_i] \right) \bar{\eta}.$$

Convexity of f therefore implies

$$f(\bar{x}) \le \sum_{\bar{\eta} \in \{0,1\}^n} \left(\prod_{i=1}^n [(1-x_i)(1-\eta_i) + x_i \eta_i] \right) f(\bar{\eta}) \quad (16)$$

with equality if $\bar{x} \in \{0,1\}^n$. Let $X_1^i := X_1, \ldots, X_i$ be the first i elements of the sequence X_1, \ldots, X_n . Let $W_i(\eta_i) = (1 - X_i)(1 - \eta_i) + X_i\eta_i$ and let $w_i(\eta_i) = (1 - b_i)(1 - \eta_i) + b_i\eta_i$. Note that by the assumption of the lemma

$$\mathbb{E}[W_i(\eta_i)|X_1^{i-1}] = \mathbb{E}[(1 - X_i)(1 - \eta_i) + X_i\eta_i|X_1^{i-1}]$$

= $(1 - b_i)(1 - \eta_i) + b_i\eta_i = w_i(\eta_i).$

By taking expectation of both sides of (16), we obtain

$$\mathbb{E}_{X_{1}^{n}}[f(X_{1}^{n})] \leq \mathbb{E}_{X_{1}^{n}} \left[\sum_{\bar{\eta} \in \{0,1\}^{n}} \left(\prod_{i=1}^{n} W_{i}(\eta_{i}) \right) f(\bar{\eta}) \right] \\
= \sum_{\bar{\eta} \in \{0,1\}^{n}} \mathbb{E}_{X_{1}^{n}} \left[\prod_{i=1}^{n} W_{i}(\eta_{i}) \right] f(\bar{\eta}) \\
= \sum_{\bar{\eta} \in \{0,1\}^{n}} \mathbb{E}_{X_{1}^{n-1}} \left[\mathbb{E}_{X_{n}} \left[\prod_{i=1}^{n} W_{i}(\eta_{i}) \middle| X_{1}^{n-1} \right] \right] f(\bar{\eta}) \\
= \sum_{\bar{\eta} \in \{0,1\}^{n}} \mathbb{E}_{X_{1}^{n-1}} \left[\prod_{i=1}^{n-1} W_{i}(\eta_{i}) \mathbb{E}_{X_{n}} \left[W_{n}(\eta_{n}) \middle| X_{1}^{n-1} \right] \right] f(\bar{\eta}) \\
= \sum_{\bar{\eta} \in \{0,1\}^{n}} \mathbb{E}_{X_{1}^{n-1}} \left[\prod_{i=1}^{n-1} W_{i}(\eta_{i}) \right] w_{n}(\eta_{n}) f(\bar{\eta}) \\
= \dots \\
= \sum_{\bar{\eta} \in \{0,1\}^{n}} \left(\prod_{i=1}^{n} w_{i}(\eta_{i}) \right) f(\bar{\eta}) \\
= \sum_{\bar{\eta} \in \{0,1\}^{n}} \left(\prod_{i=1}^{n} [(1-b_{i})(1-\eta_{i}) + b_{i}\eta_{i}] \right) f(\bar{\eta}) \\
= \mathbb{E}_{Y_{1}^{n}} [f(Y_{1}^{n})].$$

In (17), we apply induction in order to replace X_i by b_i , one-by-one from the last to the first, same way we did it for X_n .

Lemma 2 follows from the following concentration result for independent Bernoulli random variables that is based on the method of types in information theory [8]. Its proof can be found in [17], [25].

Lemma 13: Let Y_1, \ldots, Y_n be i.i.d. Bernoulli random variables, such that $\mathbb{E}[Y_i] = b$. Then

$$\mathbb{E}\left[e^{n\operatorname{kl}\left(\frac{1}{n}\sum_{i=1}^{n}Y_{i}\|b\right)}\right] \leq n+1. \tag{18}$$

For $n \geq 8$, it is possible to prove even stronger result $\sqrt{n} \leq \mathbb{E}[e^{n\operatorname{kl}(\frac{1}{n}\sum_{i=1}^n Y_i\|b}] \leq 2\sqrt{n}$ using Stirling's approximation of the factorial [19]. For the sake of simplicity, we restrict ourselves to the slightly weaker bound (18), although all results that are based on Lemma 2 can be slightly improved by using the tighter bound.

Proof of Lemma 2: Since KL-divergence is a convex function [8] and the exponent function is convex and nondecreasing, $e^{n \operatorname{kl}(p||q)}$ is also a convex function. Therefore, Lemma 2 follows from Lemma 13 by Lemma 1.

Corollary 3 follows from Lemma 2 by Markov's inequality.

Lemma 14 (Markov's Inequality): For $\delta \in (0,1)$ and a random variable $X \geq 0$, with probability greater than $1 - \delta$

$$X \le \frac{1}{\delta} \mathbb{E}[X]. \tag{19}$$

Proof of Corollary 3: By Markov's inequality and Lemma 2, with probability greater than $1-\delta$

$$e^{n\operatorname{kl}\left(\frac{1}{n}S_n \right\| b\right)} \leq \frac{1}{\delta} \mathbb{E}\left[e^{n\operatorname{kl}\left(\frac{1}{n}S_n \right\| b\right)}\right] \leq \frac{n+1}{\delta}.$$

Taking logarithm of both sides of the inequality and normalizing by n completes the proof.

APPENDIX B

PROOFS OF PAC-BAYESIAN THEOREMS FOR MARTINGALES

In this appendix, we provide the proofs of Theorems 4, 7, and 8. The proof of Theorem 5 is very similar to the proof of Theorem 7 and, therefore, omitted. The proof of Theorem 6 is very similar to the proof of Theorem 8, so we only provide the way of how to choose the grid of λ -s in this theorem.

The proofs of all PAC-Bayesian theorems are based on the following lemma, which is obtained by changing sides in Donsker–Varadhan's variational definition of relative entropy. The lemma takes roots back in information theory and statistical physics [5]–[7]. The lemma provides a deterministic relation between averages of ϕ with respect to all possible distributions ρ and the cumulant-generating function $\ln \langle e^{\phi}, \pi \rangle$ with respect to a single reference distribution π . A single application of Markov's inequality combined with the bounds on moment-generating functions in Lemmas 2, 9, and 11 is then used in order to bound the last term in (20) in the proofs of Theorems 4, 5, and 7, respectively.

Lemma 15 (Change of Measure Inequality): For any probability space $(\mathcal{H}, \mathcal{B})$, a measurable function $\phi : \mathcal{H} \to \mathbb{R}$, and any distributions π and ρ over \mathcal{H} , we have

$$\langle \phi, \rho \rangle < \text{KL}(\rho || \pi) + \ln \langle e^{\phi}, \pi \rangle.$$
 (20)

Since the KL-divergence is infinite when the support of ρ exceeds the support of π , inequality (20) is interesting when $\pi \gg \rho$. For a similar reason, it is interesting only when $\langle e^\phi, \pi \rangle$ is finite. We note that the inequality is tight in the same sense as Jensen's inequality is tight: for $\phi(h) = \ln \frac{\rho(h)}{\pi(h)}$, it becomes an equality.

Proof of Theorem 4: Take $\phi(h) := n \operatorname{kl}(\frac{1}{n} \overline{S}_n(h) || \overline{b}(h))$. More compactly, denote $\phi = \operatorname{kl}(\frac{1}{n} \overline{S}_n || \overline{b}) : \mathcal{H} \to \mathbb{R}$. Then, with probability greater than $1 - \delta$ for all ρ

$$n \operatorname{kl}\left(\left\langle \frac{1}{n} \bar{S}_{n}, \rho \right\rangle \middle\| \langle \bar{b}, \rho \rangle\right)$$

$$\leq n \left\langle \operatorname{kl}\left(\frac{1}{n} \bar{S}_{n} \middle\| \bar{b}\right), \rho \right\rangle \tag{21}$$

$$\leq \mathrm{KL}(\rho \| \pi) + \ln \left\langle e^{n \, \mathrm{kl}(\frac{1}{n} \bar{S}_n \| \bar{b})}, \pi \right\rangle \tag{22}$$

$$\leq \mathrm{KL}(\rho \| \pi) + \ln \left(\frac{1}{\delta} \mathbb{E}_{\bar{X}_{1}^{n}} \left[\left\langle e^{n \operatorname{kl}(\frac{1}{n} \bar{S}_{n} \| \bar{b})}, \pi \right\rangle \right] \right) \tag{23}$$

$$= \mathrm{KL}(\rho \| \pi) + \ln \left(\frac{1}{\delta} \left\langle \mathbb{E}_{\bar{X}_{1}^{n}} \left[e^{n \operatorname{kl}(\frac{1}{n} \bar{S}_{n} \| \bar{b})} \right], \pi \right\rangle \right) (24)$$

$$\leq \mathrm{KL}(\rho \| \pi) + \ln \frac{n+1}{\delta}$$
 (25)

where (21) is by convexity of the kl divergence [8]; (22) is by change of measure inequality (Lemma 15); (23) holds with

probability greater than $1 - \delta$ by Markov's inequality; in (24), we can take the expectation inside the dot product due to linearity of both operations and since π is deterministic; and (25) is by Lemma 2.1 Normalization by n completes the proof of the theorem.

Proof of Theorem 7: For the proof of Theorem 7, we take $\phi(h) := \lambda \bar{M}_n(h) - (e-2)\lambda^2 \bar{V}_n(h)$. Or, more compactly, $\phi =$ $\lambda \bar{M}_n - (e-2)\lambda^2 \bar{V}_n$. Then, with probability greater than $1 - \frac{\delta}{2}$ for all ρ

$$\lambda \langle \bar{M}_{n}, \rho \rangle - (e - 2)\lambda^{2} \langle \bar{V}_{n}, \rho \rangle = \langle \lambda \bar{M}_{n} - (e - 2)\lambda^{2} \bar{V}_{n}, \rho \rangle$$

$$\leq KL(\rho || \pi) + \ln \left\langle e^{\lambda \bar{M}_{n} - (e - 2)\lambda^{2} \bar{V}_{n}}, \pi \right\rangle$$

$$\leq KL(\rho || \pi) + \ln \left(\frac{2}{\delta} \mathbb{E}_{\bar{Z}_{1}^{n}} \left[\left\langle e^{\lambda \bar{M}_{n} - (e - 2)\lambda^{2} \bar{V}_{n}}, \pi \right\rangle \right] \right)$$

$$= KL(\rho || \pi) + \ln \left(\frac{2}{\delta} \left\langle \mathbb{E}_{\bar{Z}_{1}^{n}} \left[e^{\lambda \bar{M}_{n} - (e - 2)\lambda^{2} \bar{V}_{n}} \right], \pi \right\rangle \right)$$

$$\leq KL(\rho || \pi) + \ln \frac{2}{\delta}$$

$$(27)$$

where (27) is by Lemma 11 and other steps are justified in the same way as in the previous proof.

By applying the same argument to $-\bar{M}_n$, taking a union bound over the two results, taking $(e-2)\lambda^2\langle \overline{V}_n, \rho \rangle$ to the other side of the inequality, and normalizing by λ , we obtain the statement of the theorem.

Proof of Theorem 8: The value of λ that minimizes (9) depends on ρ , whereas we would like to have a result that holds for all possible distributions ρ simultaneously. This requires considering multiple values of λ simultaneously and we have to take a union bound over λ -s in step (26) of the proof of Theorem 7. We cannot take all possible values of λ , since there are uncountably many possibilities. Instead, we determine the relevant range of λ and take a union bound over a grid of λ -s that forms a geometric sequence over this range. Since the range is finite, the grid is also finite.

The upper bound on the relevant range of λ is determined by the constraint that $\lambda \leq \frac{1}{K}$. For the lower bound, we note that since $\mathrm{KL}(\rho \| \pi) \geq 0$, the value of λ that minimizes (9) is lower bounded by $\sqrt{\frac{\ln \frac{2}{\delta}}{(e-2)\langle \bar{V}_n, \rho \rangle}}$. We also note that $\langle \bar{V}_n, \rho \rangle \leq K^2 n$, since $|Z_i(h)| \leq K$ for all h and i. Hence, $\lambda \geq \frac{1}{K} \sqrt{\frac{\ln \frac{2}{\delta}}{(e-2)n}}$ and the range of λ we are interested in is

$$\lambda \in \left[\frac{1}{K} \sqrt{\frac{\ln \frac{2}{\delta}}{(e-2)n}}, \frac{1}{K} \right].$$

We cover the <u>aforementioned</u> range with a grid of λ_i -s, such that $\lambda_i := c^i \frac{1}{K} \sqrt{\frac{\ln \frac{2}{\delta}}{(e-2)n}}$ for $i = 0, \dots, m-1$. It is easy to see that in order to cover the interval of relevant λ , we need

$$m = \left\lceil \frac{1}{\ln c} \ln \left(\sqrt{\frac{(e-2)n}{\ln \frac{2}{\delta}}} \right) \right\rceil.$$

 $^2\mathrm{By}\,\mathrm{Lemma}\,2, \text{for each}\,h\in\mathcal{H}, \text{we have}\,\mathbb{E}_{\bar{X}_1^n}\left[e^{n\,\mathrm{kl}(\frac{1}{n}\,\bar{S}_n(h)\|\bar{b}(h))}\right]\leq n+1$ and, therefore, $\left\langle \mathbb{E}_{\bar{X}_{1}^{n}}\left[e^{n \operatorname{kl}\left(\frac{1}{n}\bar{S}_{n} \| \bar{b}\right)}\right], \pi \right\rangle \leq n+1.$

 (λ_{m-1}) is the last value that is strictly less than 1/K and we take $\lambda_m := 1/K$ for the case when the technical condition (10) is not satisfied.) This defines the value of ν in (12).

Finally, we note that (9) has the form $g(\lambda) = \frac{U}{\lambda} + \lambda V$. For the relevant range of λ , there is λ_{i^*} that satisfies $\sqrt{U/V} \leq \lambda_{i^*} <$ $c\sqrt{U/V}$. For this value of λ , we have $g(\lambda_{i^*}) \leq (1+c)\sqrt{UV}$.

Therefore, whenever (10) is satisfied, we pick the highest value of λ_i that does not exceed the left-hand side of (10), substitute it into (9), and obtain (11), where the $\ln \nu$ factor comes from the union bound over λ_i -s. If (10) is not satisfied, we know that $\langle \bar{V}_n,
ho
angle < K^2(KL(
ho \| \pi) + \ln rac{2
u}{\delta})/(e-2)$ and by taking $\lambda = 1/K$ and substituting into (9), we obtain (13).

Proof of Theorem 6: Theorem 6 follows from Theorem 5 in the same way as Theorem 8 follows from Theorem 7. The only difference is that the relevant range of λ is unlimited from above. If $KL(\rho||\pi) = 0$, the bound is minimized by

$$\lambda = \sqrt{\frac{8 \ln \frac{2}{\delta}}{\sum_{i=1}^{n} (\beta_i - \alpha_i)^2}}.$$

Hence, we are interested in λ that is larger or equal to this value. We take a grid of λ_i -s of the form

$$\lambda_i : c^i \sqrt{\frac{8 \ln \frac{2}{\delta}}{\sum_{i=1}^n (\beta_i - \alpha_i)^2}}$$

for $i \geq 0$. Then, for a given value of $KL(\rho || \pi)$, we have to pick λ_i , such that

$$i = \left| \frac{\ln \left(\frac{KL(\rho || \pi)}{\ln \frac{2}{\delta}} + 1 \right)}{2 \ln c} \right|$$

where |x| is the largest integer value that is smaller than x. Taking a weighted union bound over λ_i -s with weights $2^{-(i+1)}$ completes the proof. (In the weighted union bound, we take $\delta_i = \delta 2^{-(i+1)}$. Then, by substitution of δ with δ_i , (7) holds with probability greater than $1 - \delta_i$ for each λ_i individually, and with probability greater than $1 - \sum_{i=0}^{\infty} \delta_i = 1 - \delta$ for all λ_i simultaneously.)

APPENDIX C BACKGROUND

In this section, we provide a proof of Lemma 11. The proof reproduces an intermediate step in the proof of [21, Th. 1].

Proof of Lemma 11: First, we have

$$\mathbb{E}_{Z_i}[e^{\lambda Z_i}|Z_1^{i-1}] \le \mathbb{E}_{Z_i}[1 + \lambda Z_i + (e-2)\lambda^2(Z_i)^2|Z_1^{i-1}]$$
(28)

$$= 1 + (e - 2)\lambda^2 \mathbb{E}_{Z_i}[(Z_i)^2 | Z_1^{i-1}]$$
 (29)
$$< e^{(e-2)\lambda^2 \mathbb{E}_{Z_i}[(Z_i)^2 | Z_1^{i-1}]}$$
 (30)

$$\leq e^{(e-2)\lambda^2 \mathbb{E}_{Z_i}[(Z_i)^2 | Z_1^{i-1}]}$$
 (30)

where (28) uses the fact that $e^x \le 1 + x + (e-2)x^2$ for $x \le 1$ (this restricts the choice of λ to $\lambda \leq \frac{1}{K}$, which leads to technical conditions (10) and (15) in Theorem 8 and Corollary 12, respectively); (29) uses the martingale property $\mathbb{E}_{Z_i}[Z_i|Z_1^{i-1}]=0$; and (30) uses the fact that $1 + x \le e^x$ for all x.

We apply inequality (30) in the following way:

$$\mathbb{E}_{Z_{1}^{n}} \left[e^{\lambda M_{n} - (e-2)\lambda^{2}V_{n}} \right] \\
= \mathbb{E}_{Z_{1}^{n}} \left[e^{\lambda M_{n-1} - (e-2)\lambda^{2}V_{n-1} + \lambda Z_{n} - (e-2)\lambda^{2}\mathbb{E}[(Z_{n})^{2}|Z_{1}^{n-1}]} \right] \\
= \mathbb{E}_{Z_{1}^{n-1}} \left[e^{\lambda M_{n-1} - (e-2)\lambda^{2}V_{n-1}} \times \mathbb{E}_{Z_{n}} \left[e^{\lambda Z_{n}} |Z_{1}^{n-1}| \times e^{-(e-2)\lambda^{2}\mathbb{E}[(Z_{n})^{2}|Z_{1}^{n-1}]} \right] \\
\leq \mathbb{E}_{Z_{1}^{n-1}} \left[e^{\lambda M_{n-1} - (e-2)\lambda^{2}V_{n-1}} \right] \\
\leq \dots \\
\leq 1.$$
(31)

Inequality (31) applies inequality (30) and inequality (32) recursively proceeds with Z_{n-1}, \ldots, Z_1 (in reverse order).

Note that conditioning on additional variables in the proof of the lemma does not change the result. This fact is exploited in the proof of Theorem 7, when we allow interdependence between multiple martingales.

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